## **2023 CIRES Rendezvous**

# **Deriving PBL Properties with Aircraft Data and Comparing** to the HRRR model



## **1. PBL Height as a Metric**

- The Planetary Boundary Layer (PBL) is the well mixed, lowest layer of the atmosphere
- The PBL Height (PBLH) is driven by a complex combination of lower atmosphere and surface processes (radiative heating, sfc roughness, etc)
- Getting PBLH correct is important for many applications (pollution, fog, severe weather/turbulence, wind energy, etc)
- Free Troposphere Capping inversion **Residual L** Stable BL 12
- Due to radiative heating, the PBL transitions from a nocturnal/stable (low) PBLH to a daytime/convective (high) PBLH each day
- PBLH is a simple metric that can effectively evaluate a model's ability to represent many of these processes, which are often lacking in model verification

## 2. AMDAR Aircraft Data

- Aircraft data is the most important DA source (James et al. 2020), but is not well utilized for model verification
- Aircraft Meteorological DAta Relay (AMDAR) data is one of the only sources of lower atmosphere profiles with temporal frequency (which is needed to represent the PBL)
- AMDAR provides thousands of T, humidity, and wind measurements per **hour** [hourly netcdf files with 1-d fields]



## 3. Theta-Increase PBLH Method

PBLH can be computed using AMDAR met data by finding an increase in potential temperature (theta) from a base value (typically 1.0 – 2.5 K)



## Theta-increase method example

- Step 1: Define alt\_base (200 m)

- theta-increase (290.8 + 1.5 = 292.3 K) (1142 m)
- **HRRR model PBLH**)

# 4. Project Goals/Approach

- Develop a robust algorithm to compute daytime convective PBLH from AMDAR data
- Download 1 month (1-31 July 2022) of AMDAR (netcdf) and HRRR-op (grib2) files
- Create standalone python script to test different algorithms/design settings
- Apply this PBLH algorithm to four airports (Denver, Dallas, Minneapolis, Boston)
- Analyze/plot various implementations and settle on a final design
- 2. Integrate the algorithm as a METplus use case available to the DTC community
  - Use a modified point-observations use case (MET tool "point-stat") Convert standalone python script to a METplus use case python script (which
  - creates a pandas dataframe and sends 11-column ASCII table to MET) Create conf file (PointStat\_pblh.conf) that calls the python script at specified times and settings
  - Run MET through location masks (using Gen-VX-mask) to filter data near airports
- 3. Implement the product into GSL's METexpress product
  - Run the METplus use case to generate .stat files for both AMDAR and HRRR • Ingest the .stat files into METexpress
  - Allow the selection of various settings in METexpress
  - Airport: Denver, Dallas, Minneapolis, Boston
  - Sounding: Ascent, Descent, All
  - PT\_Delta (K): 1.25, 1.75

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### **Initial Algorithm Settings**

- Include the following AMDAR aircraft data:
- Ascents/Descents (discard all cruising flights)
- 110 km); 0.3 deg had not enough flights; 1.0 deg was similar to 0.7 deg]
- Flight must contain at least 4 data points
- Flight data point below PBLH must be < gap\_max (400 + PBLH/20 m)

## **Initial PBLH Scatterplot**

- Interpolated values are less than closest values esp at larger gaps
- A few outliers of large negative gaps due to arrays being out of order [this occurs when an ascending or descending flight briefly goes up and down]

## **Reordering all arrays**

- Reordering all arrays to be ascending eliminates the gap outliers
- Some negative PBLH values due to flight altitude arrays starting with negative values (since ground height is uneven around airport)
- Changing Denver ground ht from 5430 to 5300 ft reduced negative instances

### Adjusting alt\_min to zero

- Forcing negative altitude arrays to start at zero eliminates the negative **PBLH** values
- This produces a PBLH "bottom" for closest data point values (and increases interpolated values as well)

## **Daily Cycle**

- AMDAR at PT delta = 1.25 K (same setting as HRRR) compares well with HRRR from 12-18 UTC, but has a lower daytime peak (18-22 UTC) and collapses faster
- AMDAR at PT\_delta = 1.75 K daytime peak compares well with HRRR, but still collapses faster
- AMDAR PBLH using a r=0.3 deg radius for flight data is much lower than using a r=0.3 deg radius, due to excluding most flights / large error bars Flight sounding (ascents vs descents) produced similar PBLH values
- daytime peak, but is too high around 12 UTC (and is by definition less accurate)
- unrealistic outliers, but had only small impacts on monthly average PBLH:
  - Changing ground height from 5430 to 5300 ft
  - Forcing negative altitudes to zero
  - Rejecting outliers (discarding any data points outside of 2\_sigma std dev)













